



Evaluating staged investments in critical infrastructure for climate adaptation

Interdisciplinary Ph.D. Workshop in Sustainable Development 2019

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The really big picture

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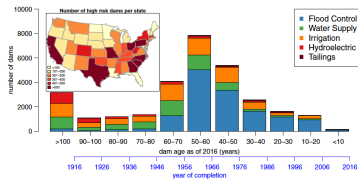


Figure 1. Age of dams in the United States (that meet the criteria of 1. Possible or likely loss of human life in the event of dam failure; 2. Dam height ≥ 7.6 m and reservoir storage $\geq 18.5 \times 10^6 \text{ m}^3$ or 3. Dam height ≥ 1.8 m and reservoir storage $\geq 61.7 \times 10^6 \text{ m}^3$) with primary uses of flood control, water supply, irrigation, hydroelectric, or tailings dams [U.S. Army Corps of Engineers, 2015] and (inset) Number of high-risk dams per state (where failure or misoperation would result in the probable loss of human life [Federal Emergency Management Agency, 2004]. Data from Stanford University [2016].

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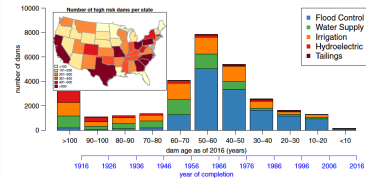
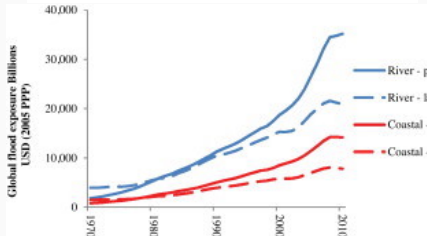
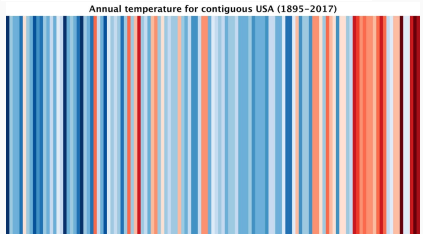


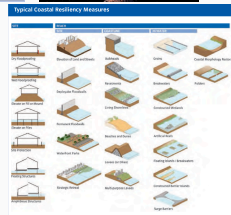
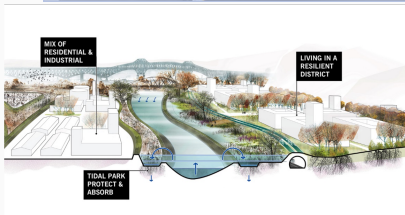
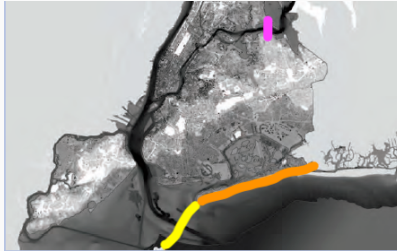
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(Ho et al., 2017; Jongman et al., 2012; “Powerless” 2016)

Motivating case study

What to do after Sandy? (City of New York, 2013)



My perspective: sequential planning under uncertainty

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Paper submitted to Earth's Future; all codes are available at
[http://github.com/jdoss-gollin/
2018-robust-adaptation-cyclical-risk](http://github.com/jdoss-gollin/2018-robust-adaptation-cyclical-risk)

Hypotheses

Idea 1: Risk Estimates over Finite Future Periods

Typical Approach:

Cost-Benefit Analysis (CBA), probably with discounting, over a finite planning horizon of M years.

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Small M : defer large investment and allow some uncertainties to be resolved

Idea 2: Hydroclimate Systems Vary on Many Scales

Inter-annual to multi-decadal cyclical variability key (for small M)

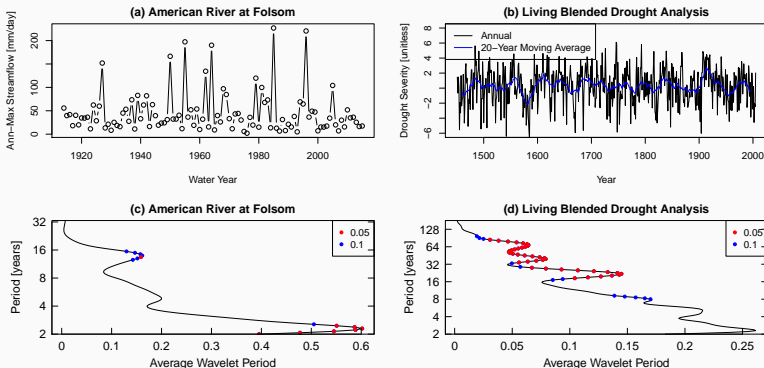
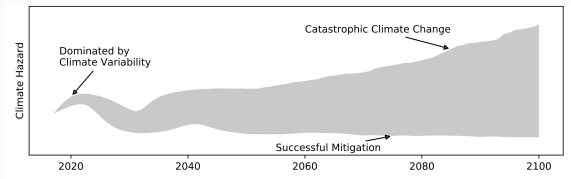


Figure 1: (a) 500 year reconstruction of summer rainfall over Arizona from LBDA (Cook et al., 2010). (b) A 100 year record of annual-maximum streamflows for the American River at Folsom. (c),(d): wavelet global (average) spectra.

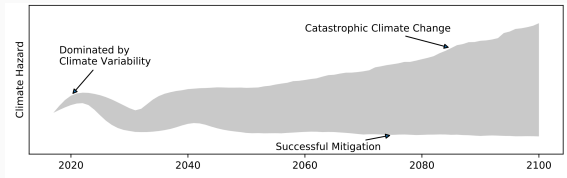
Idea 3: Physical Drivers of Risk Depend on M

The physical drivers of hazard depend on the projection horizon (M),

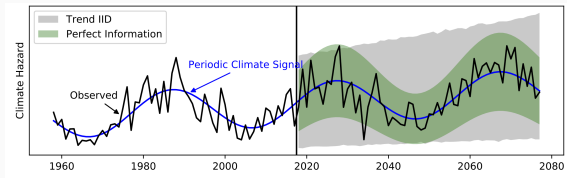


Idea 3: Physical Drivers of Risk Depend on M

The physical drivers of hazard depend on the projection horizon (M),



but our ability to identify these mechanisms depends on information available (e.g., the length of an N -year observational record).



Stylized Experiments

Experiment Setup

Research Objective

How well can one identify & predict cyclical and secular climate signals over a finite planning period (M), given limited information?

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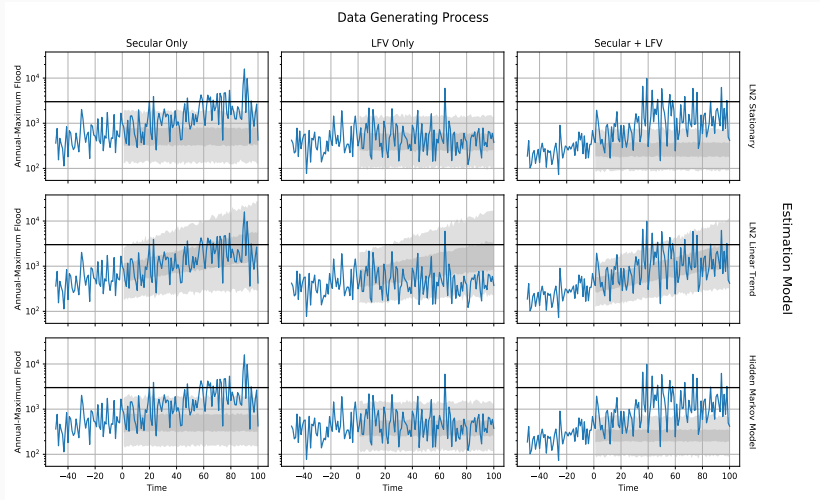
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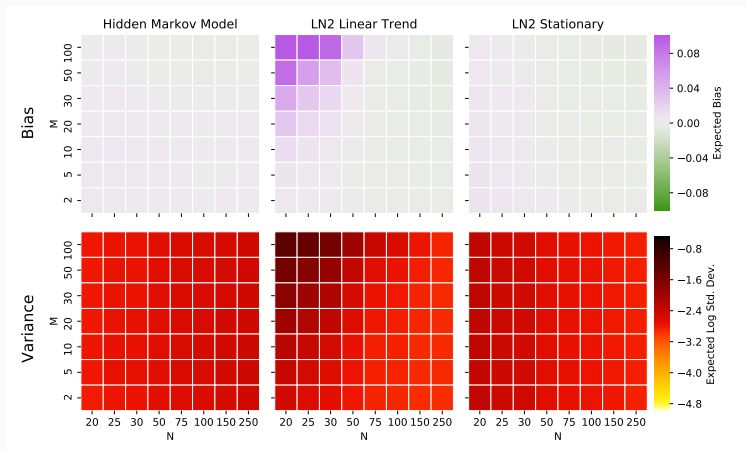
Don't use these models for actual estimation!

How it works



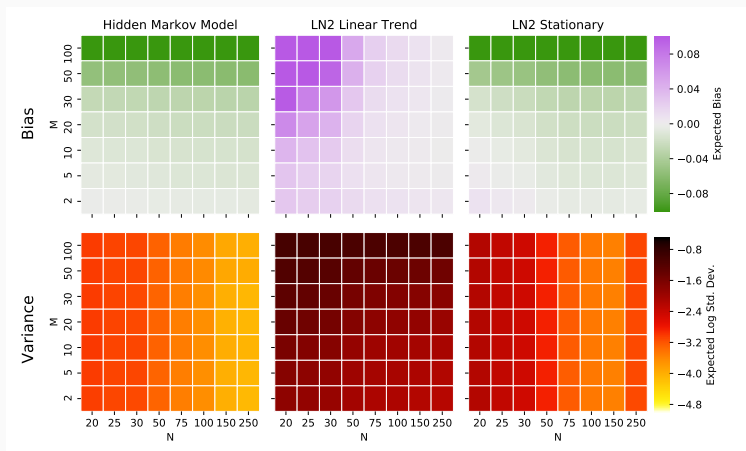
Stationary Scenario (LFV Only)

With limited data, the uncertainties caused by extrapolating from complex models lead to poor performance.



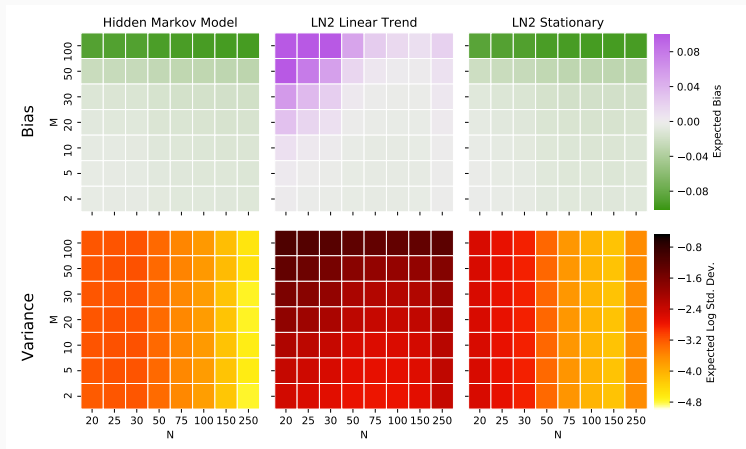
Nonstationary Scenario I (Secular Change Only)

Long planning periods need trend estimation, but this demands lots of information. For short planning periods, simple models may be better.



Nonstationary Scenario II (Secular Change + LFV)

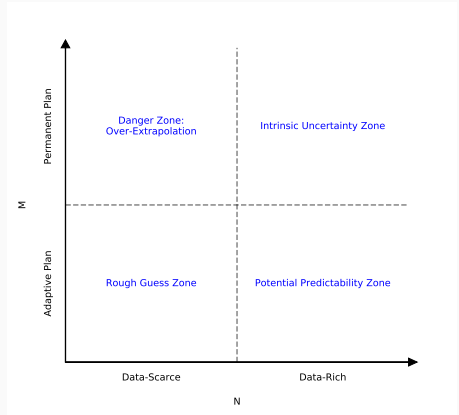
As the system becomes more complex, more data is needed to understand it.



Discussion

Summary

- Investment evaluation depends on climate condition over finite planning period
- Physical hydroclimate systems vary on many scales
- Physical drivers of risk depend on planning period



Conclusions

- Quasi-periodic and secular climate signals, with different identifiability and predictability, control future uncertainty and risk

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- Adaptation strategies need to consider how uncertainties in risk projections influence success of decision pathways
- Stylized experiments reveal how bias and variance of climate risk projections influence risk mitigation over a finite planning period

Next steps

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Thanks for your attention!

Interested in making these ideas more concrete? I'd love to collaborate!



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Supplemental Discussion

Idealized Experiments \iff Real World

The idealized models used here are analogs:

Analysis	Real World
N -year record	Total informational uncertainty of an estimate
Statistical models of increasing complexity and # parameters	Statistical and dynamical model chains of increasing complexity and # parameters
Linear trends	Secular changes of unknown form
low-frequency climate variability (LFV) from the El Niño-Southern Oscillation (ENSO)	LFV from many sources
LFV and trend additive	LFV and trend interact

Generating Synthetic Streamflow Sequences

Equations for Synthetic Streamflow Generation

First

$$\log Q(t) \sim \mathcal{N}(\mu(t), \sigma(t)). \quad (\text{A1})$$

Where $\sigma(t) = \xi\mu(t)$, with $\sigma(t) \geq \sigma_{\min} > 0$. Then,

$$\mu(t) = \mu_0 + \beta x(t) + \gamma(t - t_0), \quad (\text{A2})$$

and where $x(t)$ is NINO3.4 index from realistic ENSO model (Ramesh et al., 2016; Zebiak and Cane, 1987)

Spectrum of LFV Used

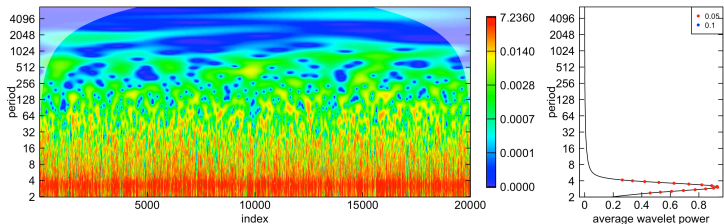


Figure A1: Wavelet spectrum of (sub-set of) ENSO model used to embed synthetic streamflow sequences with low-frequency variability. ENSO data from Ramesh et al. (2016).

Climate Risk Estimation

Stationary LN2 Model

Treat the N historical observations as independent and identically distributed (IID) draws from stationary distribution

$$\begin{aligned}\log Q_{\text{hist}} &\sim \mathcal{N}(\mu, \sigma) \\ \mu &\sim \mathcal{N}(7, 1.5) \\ \sigma &\sim \mathcal{N}^+(1, 1)\end{aligned}\tag{A3}$$

where \mathcal{N} denotes the normal distribution and \mathcal{N}^+ denotes a half-normal distribution. Fit in Bayesian framework using stan (Carpenter et al., 2017).

Trend LN2 Model

Treat the N historical observations as IID draws from log-normal distribution with linear trend

$$\begin{aligned}\mu &= \mu_0 + \beta_\mu(t - t_0) \\ \log Q_{\text{hist}} &\sim \mathcal{N}(\mu, \xi\mu) \\ \mu_0 &\sim \mathcal{N}(7, 1.5) \\ \beta_\mu &\sim \mathcal{N}(0, 0.1) \\ \log \xi &\sim \mathcal{N}(0.1, 0.1)\end{aligned}\tag{A4}$$

where ξ is an estimated coefficient of variation. Also fit in stan.

Hidden Markov Model

Two-state Hidden Markov Model (HMM) (see Rabiner and Juang, 1986) implemented using pomegranate python package (Schreiber, 2017). See package documentation for reference.