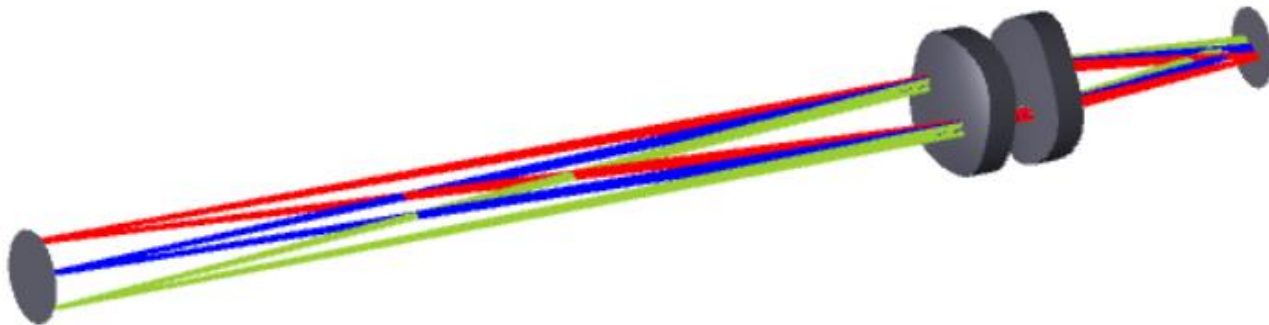


# Variable Focus Machine Vision Lens Without Moving Parts:

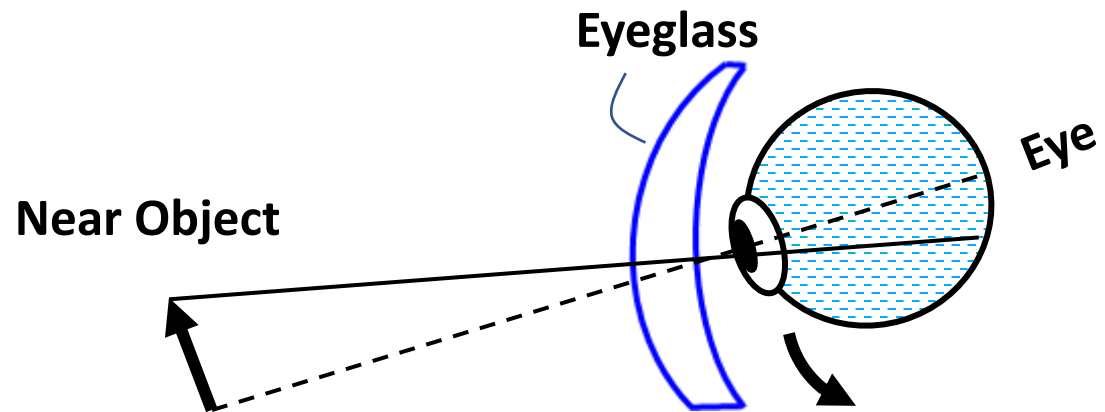
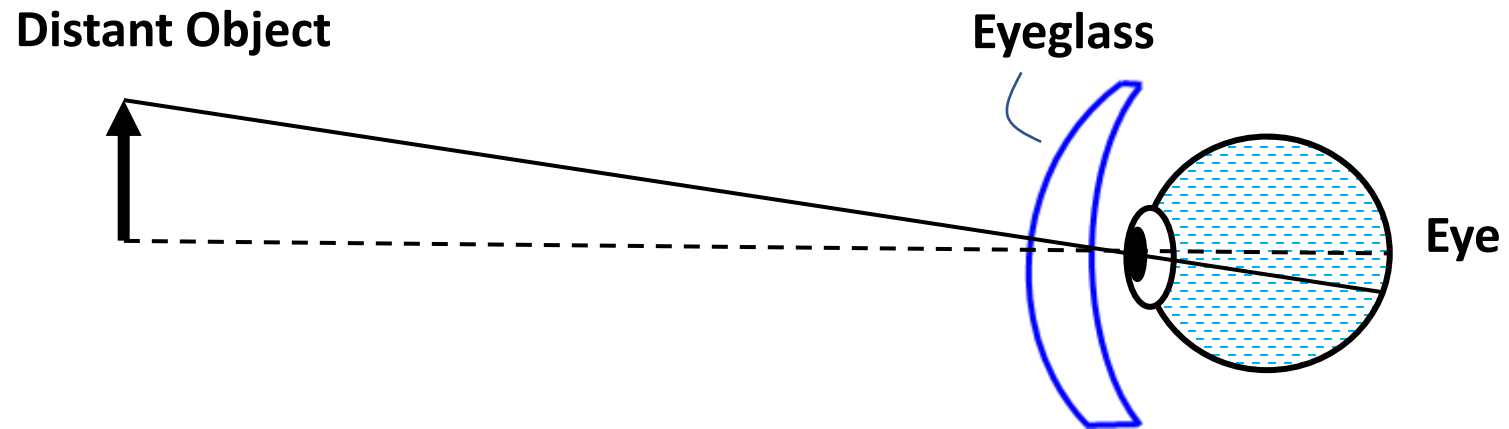
*Freeform Progressive Eyeglasses for Non-Humans*

**RONIAN SIEW**

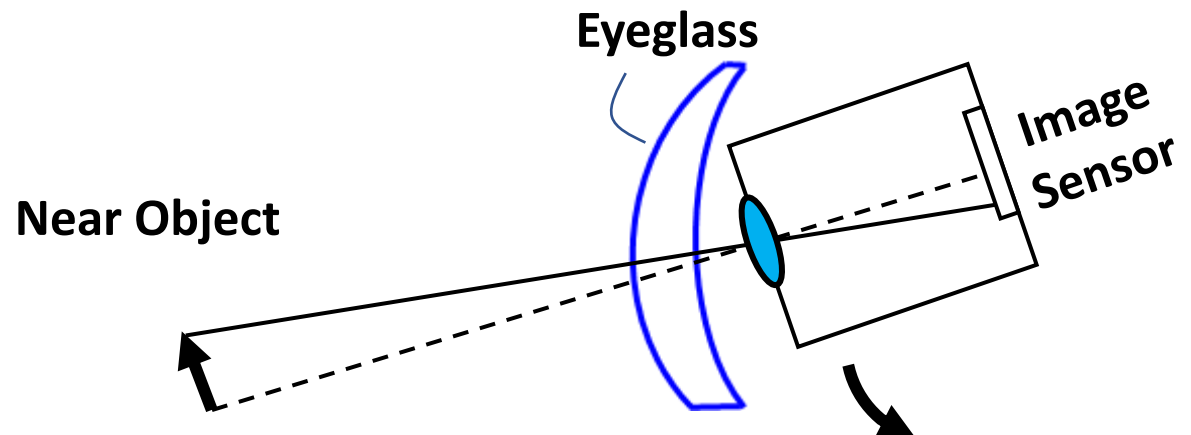
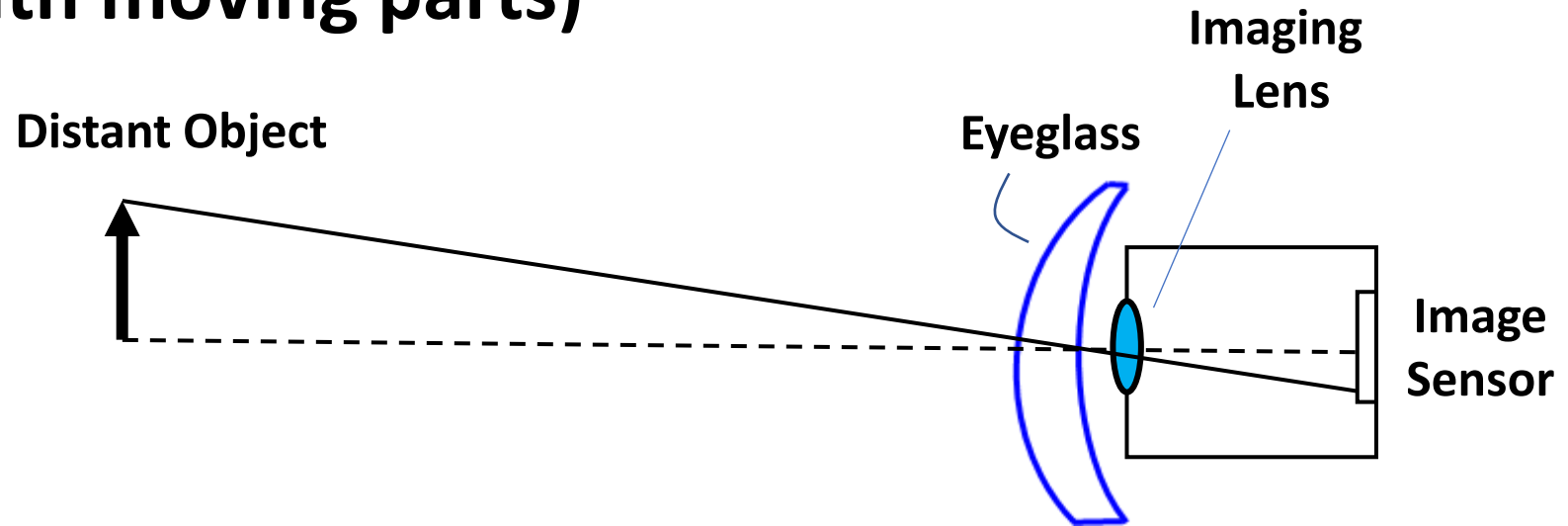


© 2020 Ronian Siew, May 21, 2020, Rev. 4  
(Prepared for the OSA Applied Optics and Imaging Congress, Online, June 25th, 2020)

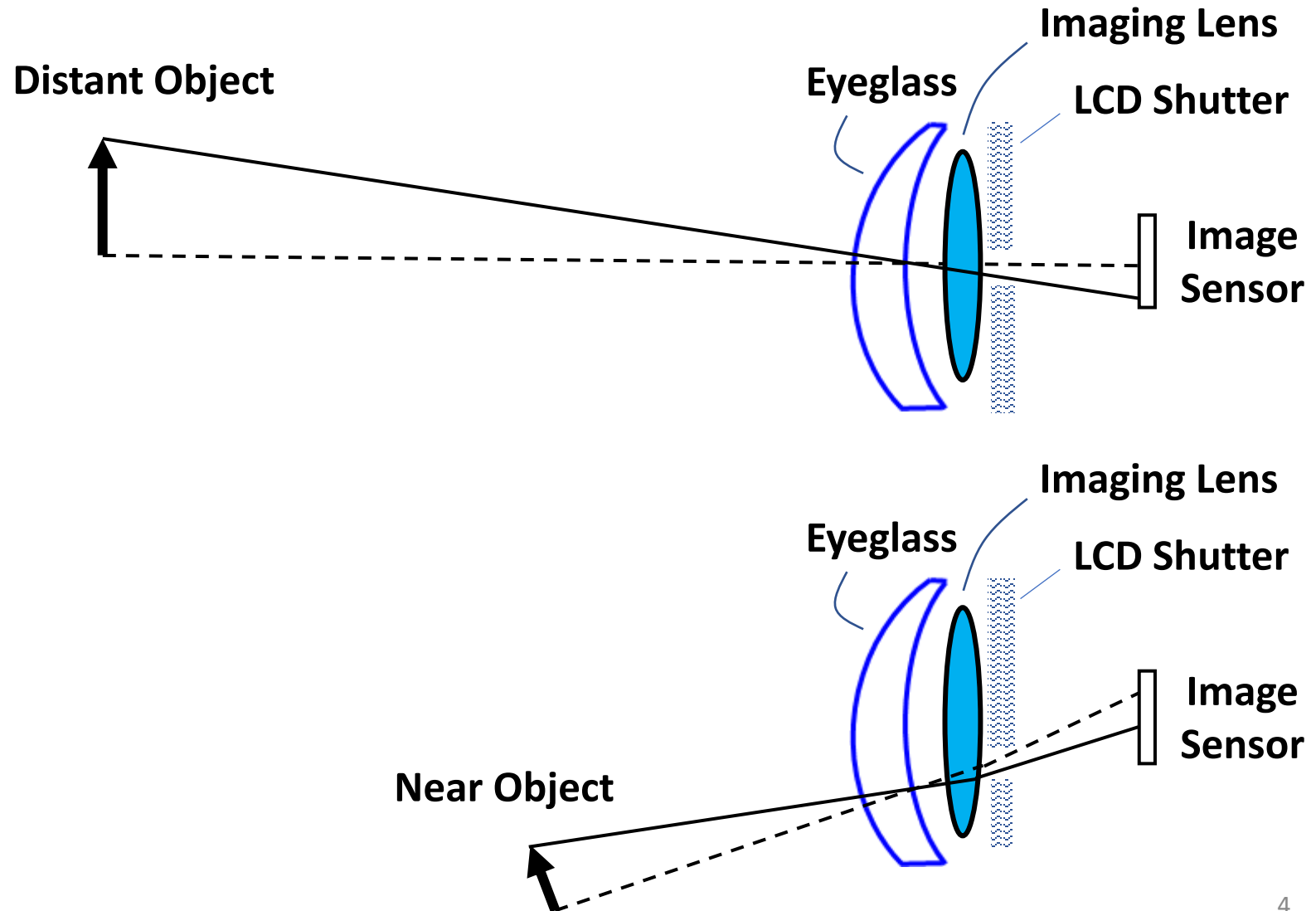
# Progressive eyeglasses for humans



# Progressive eyeglasses for a non-human (with moving parts)



# Progressive eyeglasses for a non-human (without moving parts)

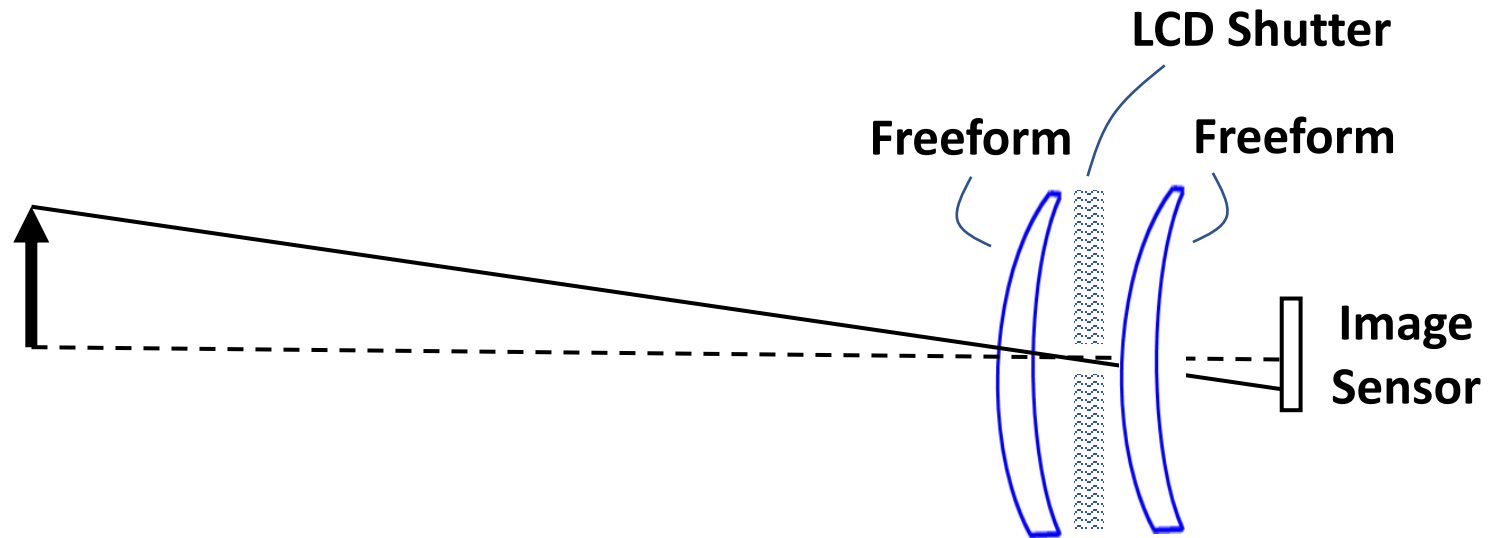


## **PRIOR ART: Discrete focal lengths**

[1] K. E. Kuijk, “Optical Imaging System Having an Electronically Variable Focal Length and Optical Image Sensor Provided with such a System,” U.S. Patent No. 4,927,241, (May 22, 1990).

[2] T. Gustafsson and S. Zyra, “Lens with Variable Focal Length,” WIPO Patent Application No. WO/1998/027448, (Dec. 17, 1997).

# CURRENT WORK: Continuous focal lengths by applying freeform surfaces



# Lens prescription for the freeform system

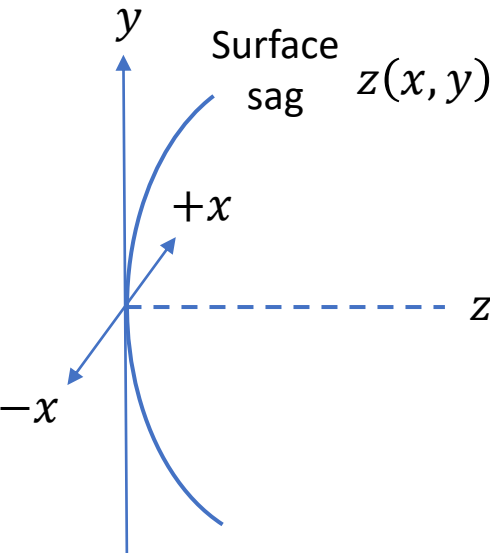
Surf	Radius	Thickness	Material	Semi-Dia	Conic	Coeff. A
OBJ	Infinity	250.00	-	-	-	-
1	Infinity	5.00	-	-	-	-
2	58.638	6.00	N-LAK22	18.00	-6.956	-6.33402E-04
3	-127.173	4.00	N-SF6	18.00	-	-
4	772.599	5.00	-	18.00	-1042.18	-4.34842E-04
STOP	Infinity	5.00	-	1.50	-	-
6	57.595	6.00	N-LAK22	18.00	-1.121	5.63615E-04
7	-132.628	4.00	N-SF6	18.00	-	-
8	606.761	57.38	-	18.00	-3.257E+30	6.26372E-04
IMG	Infinity	0.00	-	8.00	-	-

## NOTES:

1. Length dimensions are in mm
2. Set wavelengths at 450 nm, 550 nm, and 650 nm (weight = 1 each)
3. Set the field points at +/- 2.5 deg., so the full field of view is 5 degrees
4. Don't forget to aim the chief ray into the entrance pupil

# The coefficient “A” and conic are defined by the following formula for surface sag

*Surface Sag*  $z(x, y) = \frac{\overset{c = 1/\text{Radius}}{c(x^2 + y^2)}}{1 + \sqrt{1 - \underset{\text{Conic}}{(1 + k)c^2[x^2 + y^2]}}} + \overset{\text{Coefficient A}}{Ayx^2}$



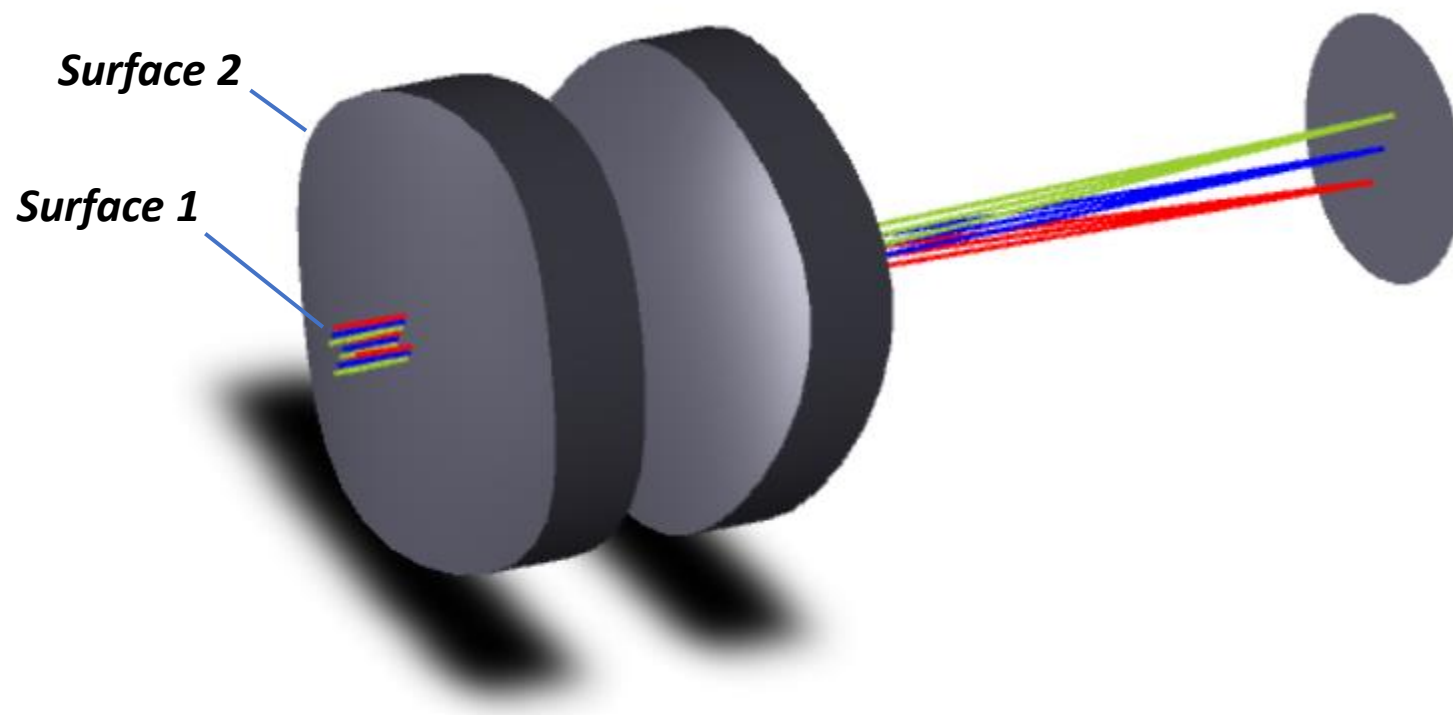
**NOTE !**

- In Zemax® OpticStudio® (which I am using), this is an “Extended Asphere” surface type
- This sag profile only applies to the +y direction of the lens system

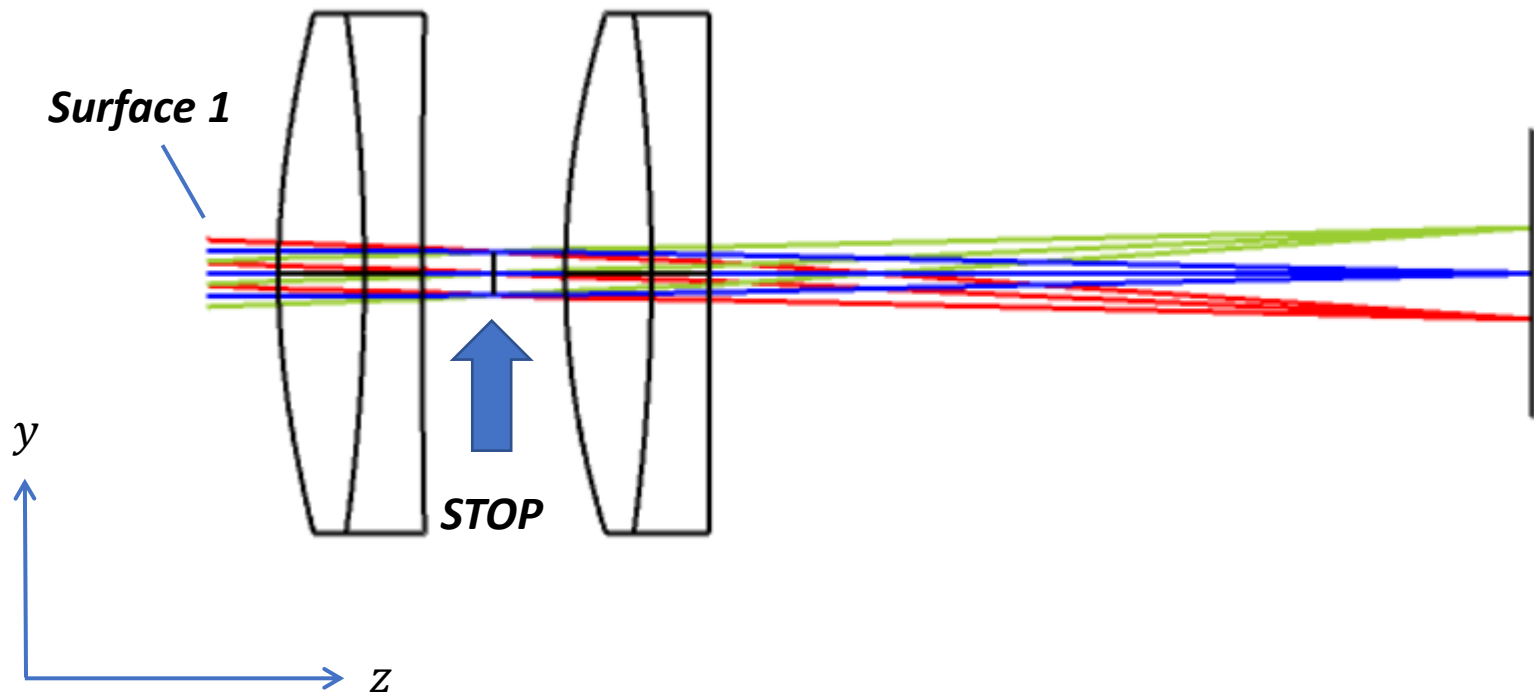


# Applying field heights at $\pm 2.5$ degrees, the 3D model of the lens system looks like this

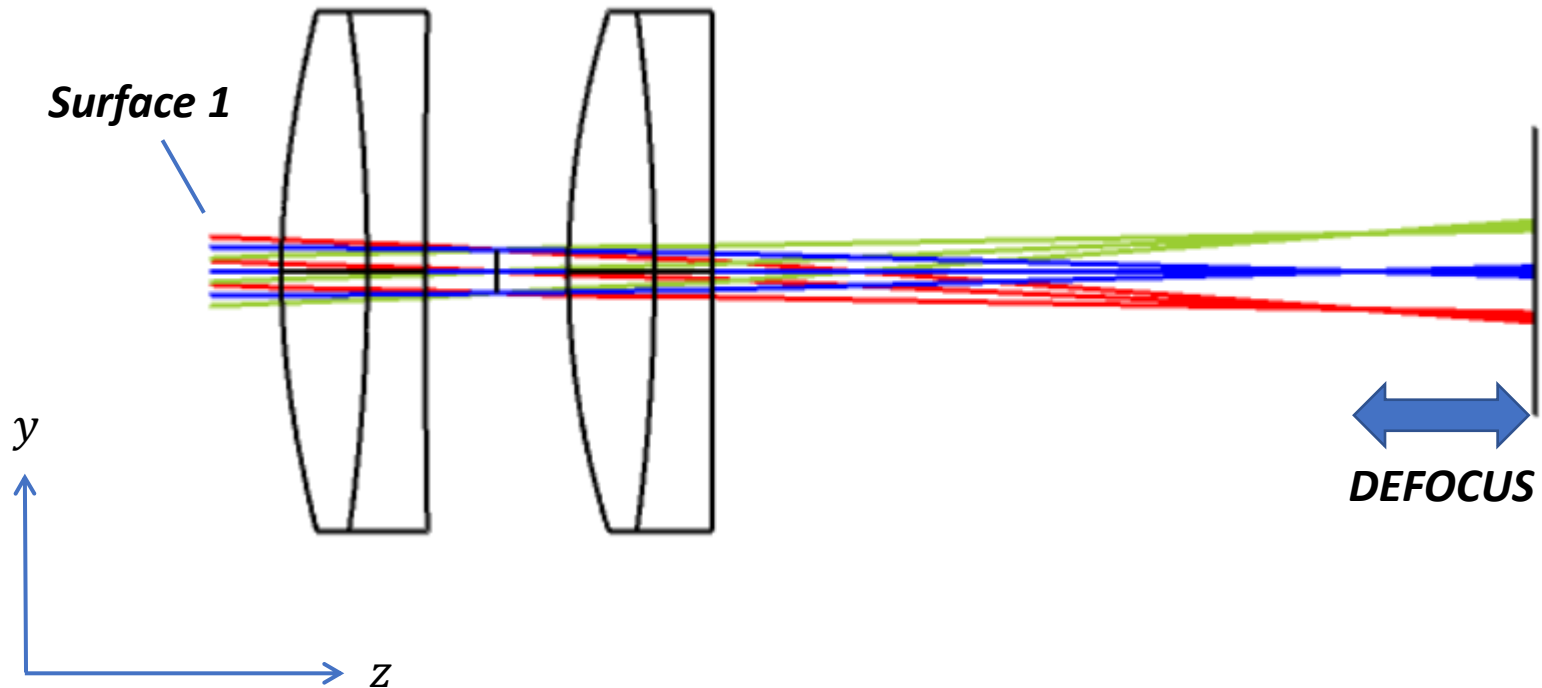
**Note:** Layout rays are shown at wavelength of 550 nm only



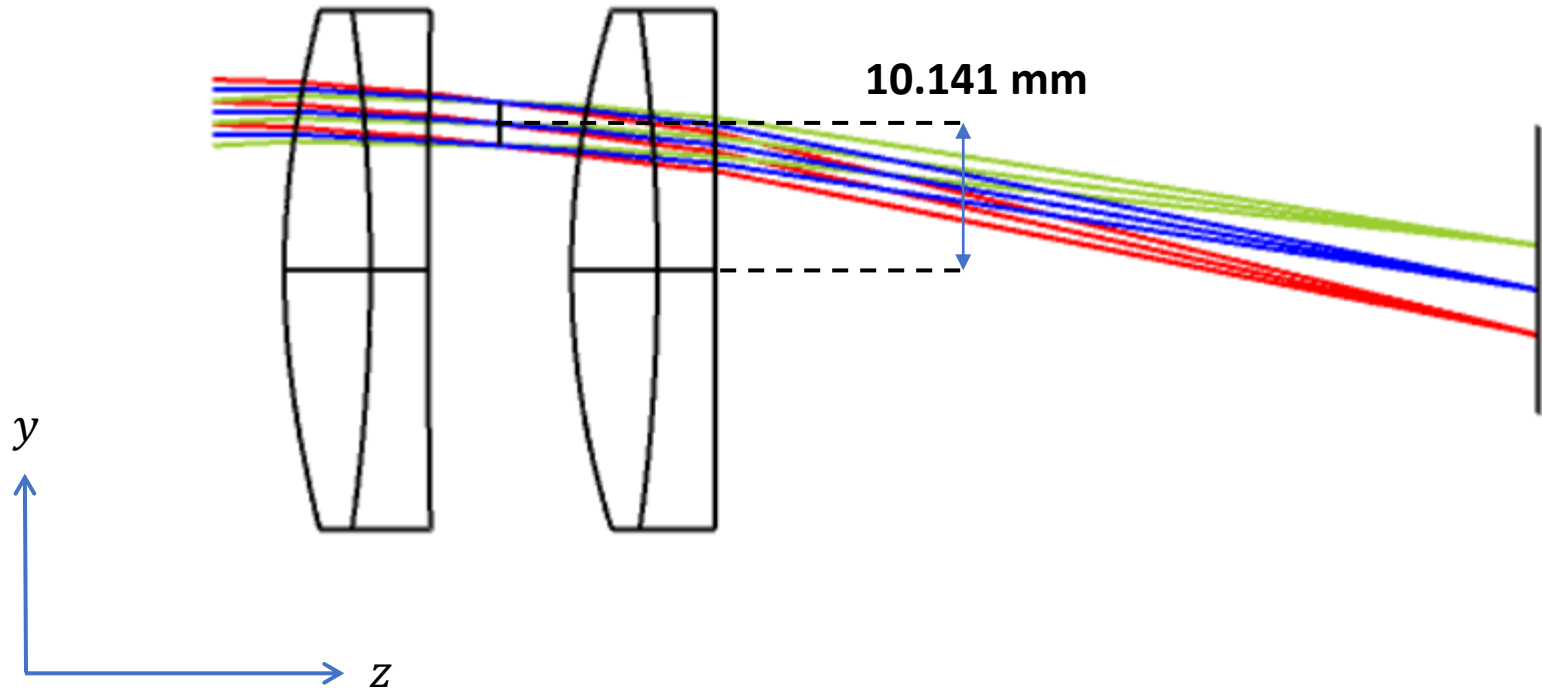
It looks like this in the  $y$ - $z$  plane (cross-section)



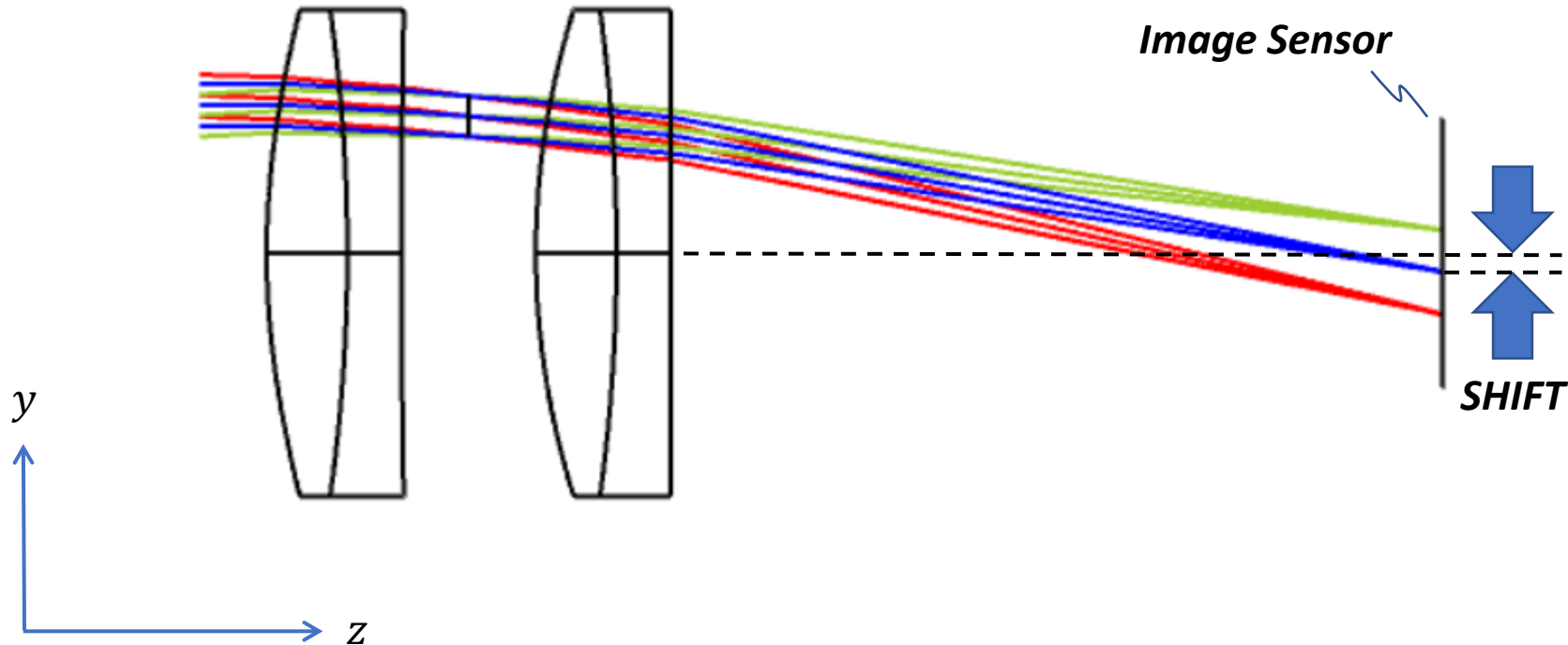
**Now, set the object distance to 1000 mm from surface 1, and the image will be defocused**



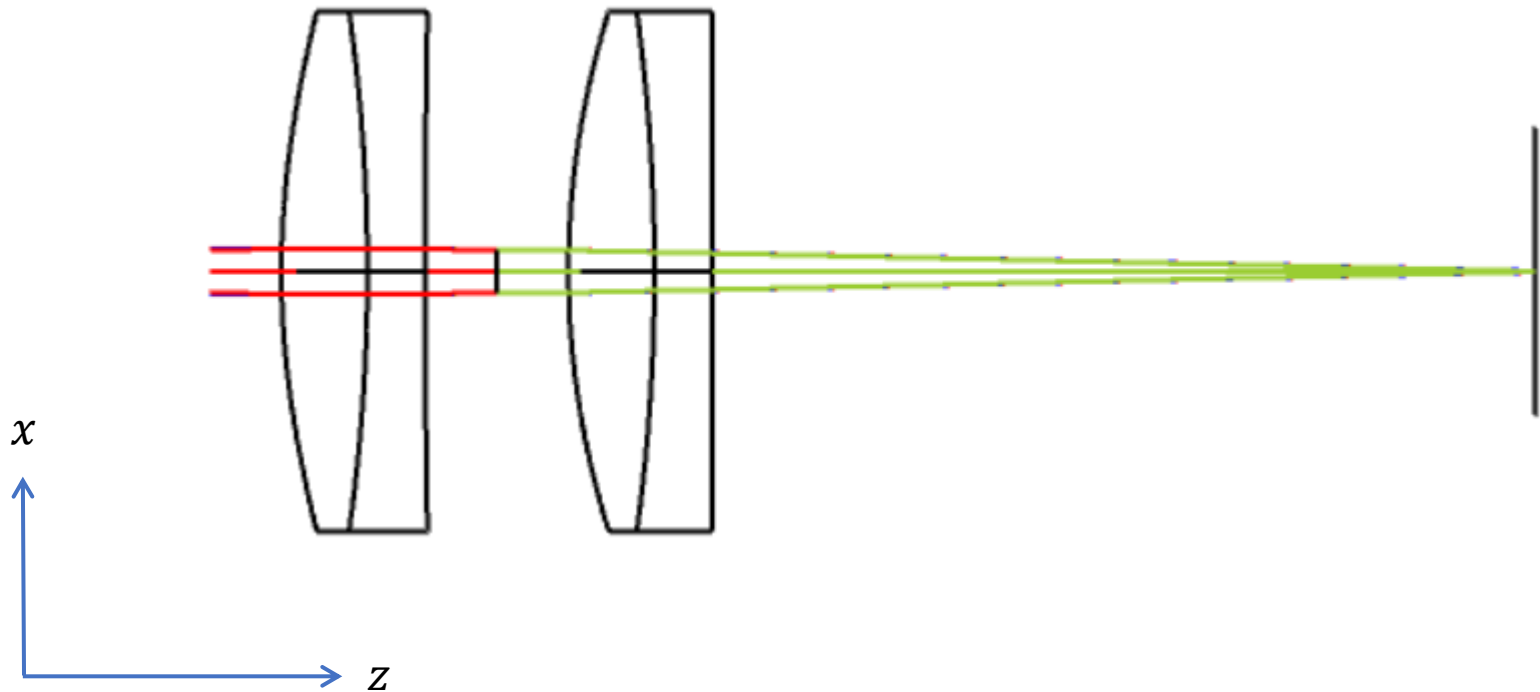
**Now, shift the stop by 10.141 mm above the optic axis, and the image is back in focus**



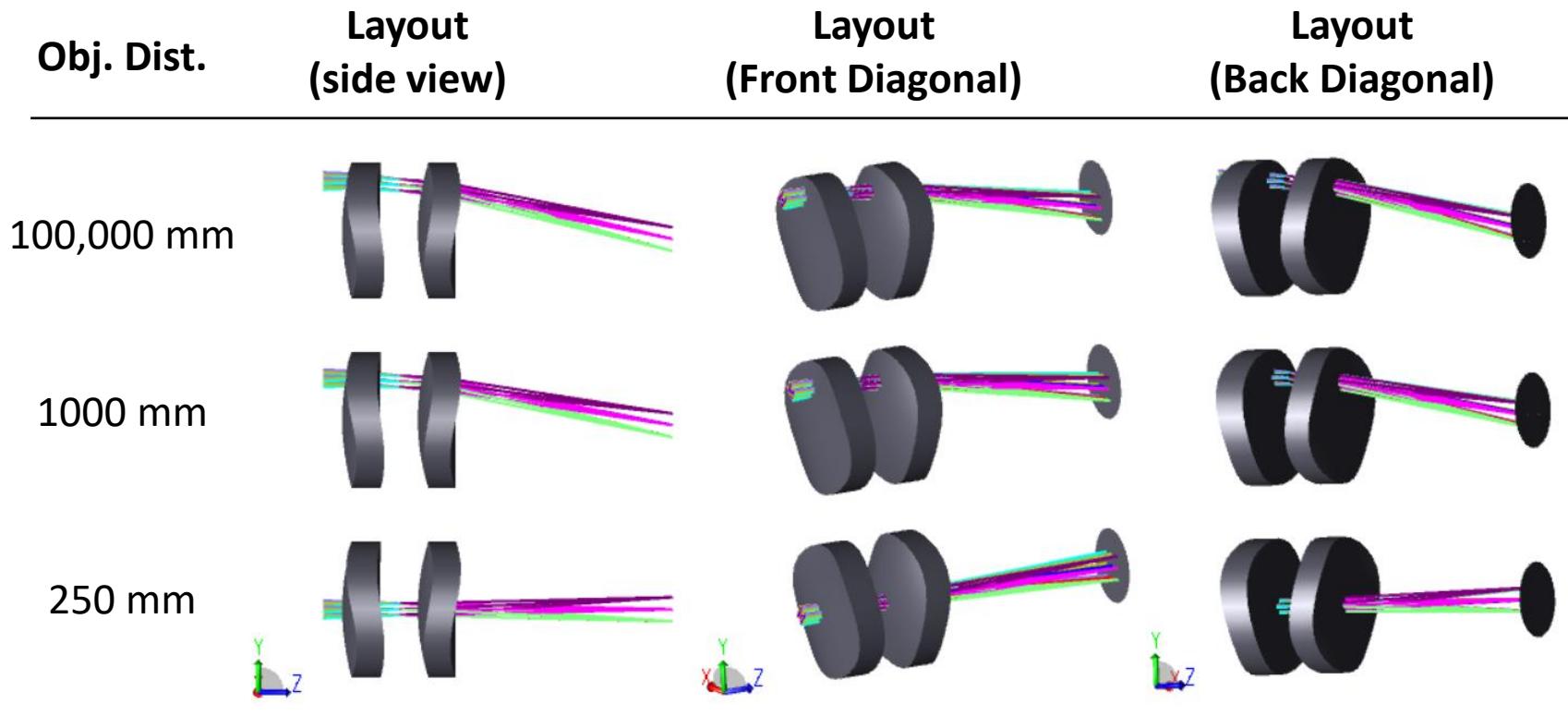
There is a shift in image height, but it can perhaps be calibrated-out computationally



**Rotate  $90^\circ$  about the z-axis and see that it's also focused for the sagittal rays**



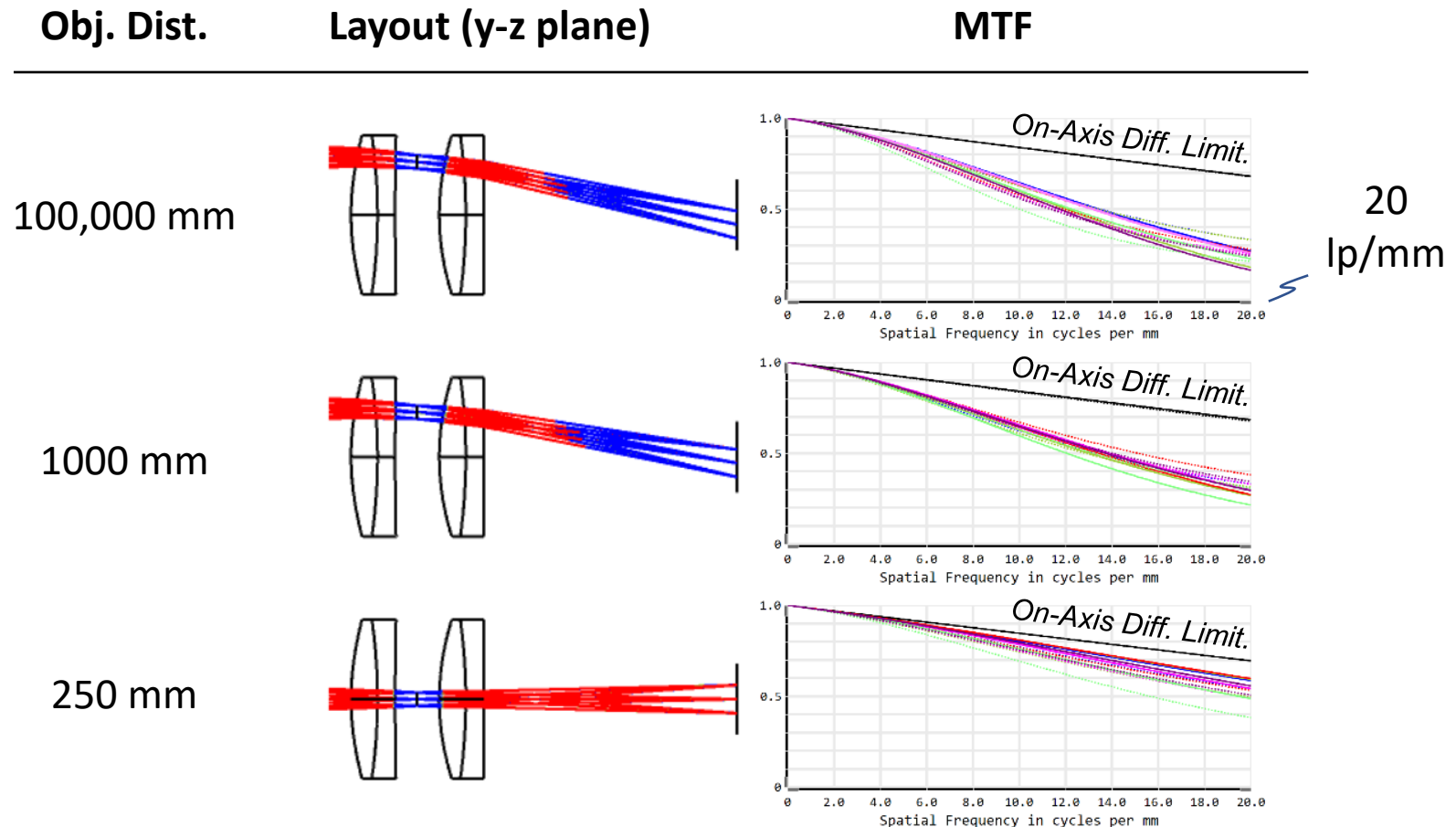
# Perspective views of the lens system for three object distances at nine field points\*



\* Nine angular field points ( $\theta_x, \theta_y$ ) at:  $(0^\circ, 0^\circ)$ ,  $(0^\circ, +2.5^\circ)$ ,  $(0^\circ, -2.5^\circ)$ ,  $(+2.5^\circ, 0^\circ)$ ,  $(-2.5^\circ, 0^\circ)$ ,  $(+2.5^\circ, +2.5^\circ)$ ,  $(+2.5^\circ, -2.5^\circ)$ ,  $(-2.5^\circ, -2.5^\circ)$ ,  $(-2.5^\circ, +2.5^\circ)$

\*\* Stop height is at 0 mm, 10.141 mm, and 12 mm at object distance 250 mm, 1000 mm, and  $10^5$  mm, respectively

# Check polychromatic MTF at 450, 550, and 650 nm (weight = 1 at each wavelength\*)

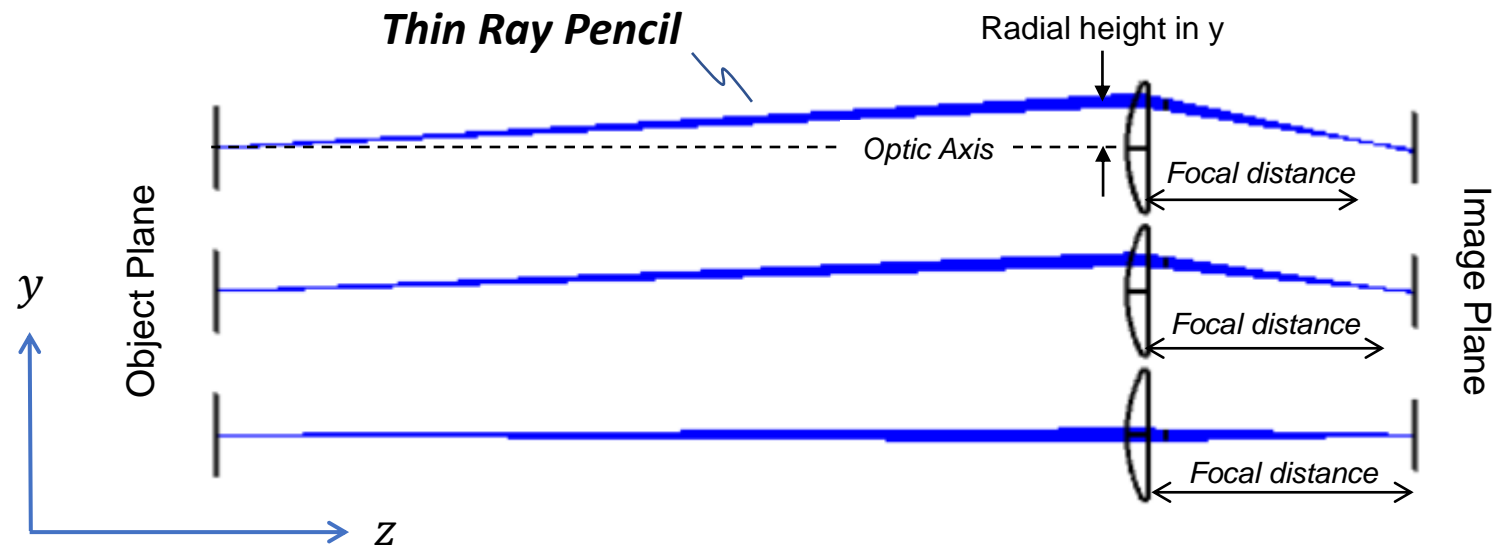


\* The rays look “colored” because the layout consists of all three wavelengths overlapping



# Design Theory

- ➔ For thin ray “pencils”, Coddington’s equations (sometimes also called “Thomas Young’s astigmatic formulas”) tell us that spherical surfaces possess natural focal length for tangential and sagittal rays, as a function of radial height above the optic axis



# Design Theory



For any rotationally symmetric surface, paraxial focal power is always given by a sag that's quadratic with radial height. For a plano-convex lens, if the convex surface is made aspheric, it can be shown\* that, for an appropriate choice of the conic constant, the focal length for a thin pencil of tangential rays can be controlled with radial height:

$$\frac{1}{f(y)} = (n - 1) \underbrace{\frac{1}{R(y)}} = (n - 1) \frac{2cy^2}{1 + \sqrt{1 - (1 + k)c^2y^2}}$$

Effective focal length of a plano-convex “sub-aperture lens” for a thin ray pencil, where the local base radius for the ray pencil has been made variable with radial height  $y$

\* R. Siew, “Progressive lens approach to variable focus without moving parts in electronic imaging systems,” Inopticalsolutions open access technical note (Jan, 2018); DOI: <https://dx.doi.org/10.6084/m9.figshare.5786733>

# Design Theory



To correct the astigmatism in the thin ray pencil, an additional term – quadratic in  $x$  but linear in  $y$  – may be applied to the surface

$$\frac{1}{f(x, y)} = \frac{2c(n-1)(x^2 + y^2)}{1 + \sqrt{1 - (1+k)c^2(x^2 + y^2)}} + Ayx^2$$

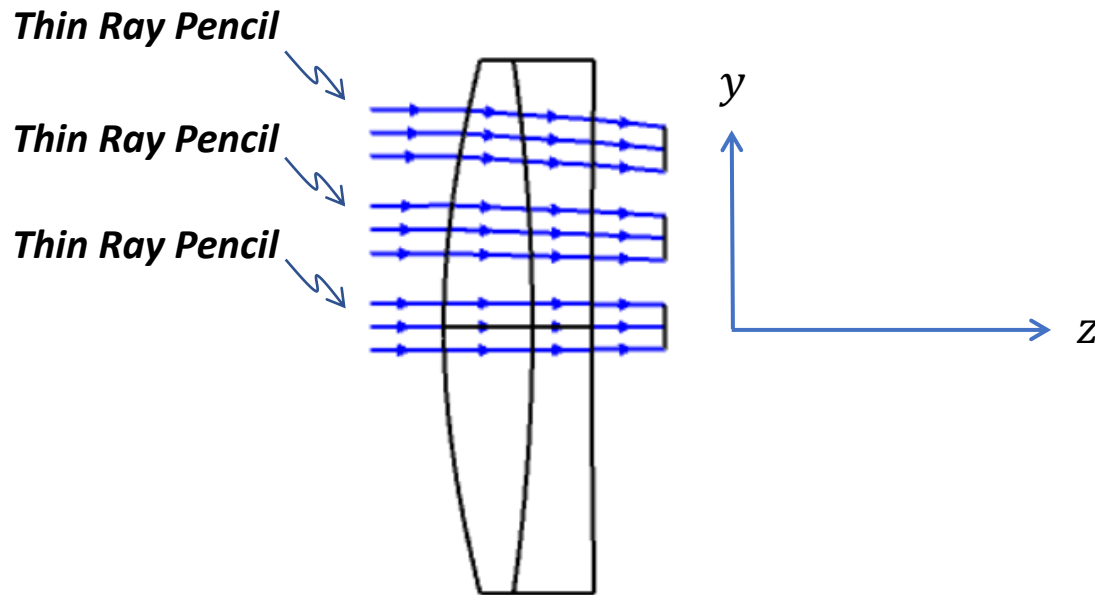
Provides power control for sagittal rays

Provides power control for tangential rays for  $x=0$

# Design Theory

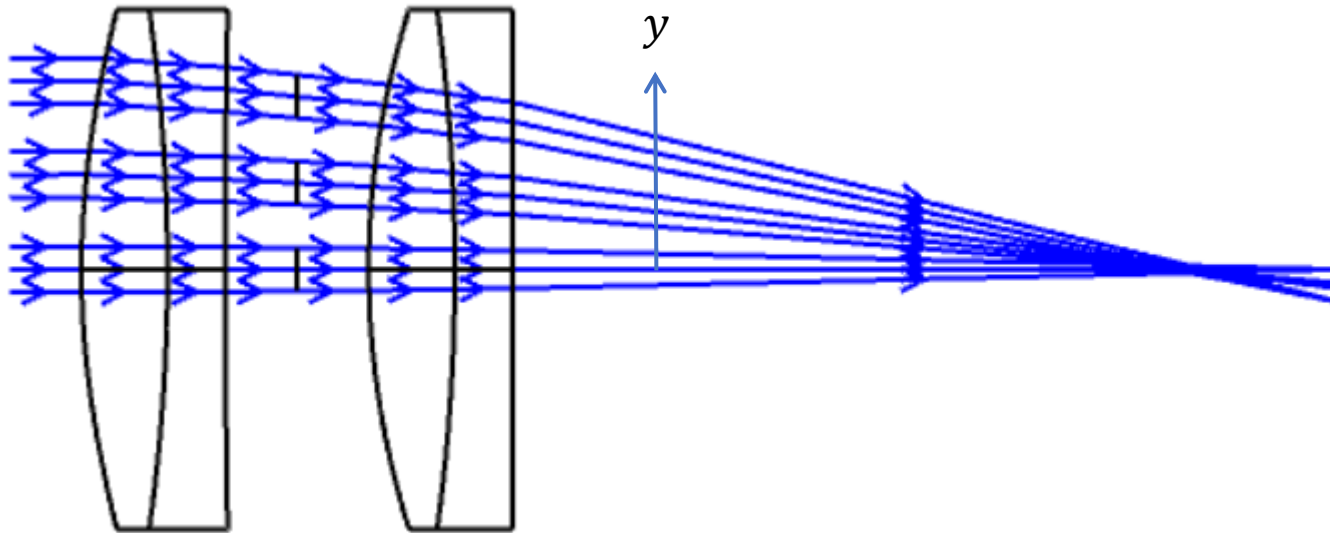
➔ To correct primary color, ray pencils at any radial height  $y$  must “see” an achromatic doublet satisfying the usual power relations (this is why two conics per doublet were used in the lens prescription):

$$\phi_1(y) = \frac{\phi(y)}{1 - \frac{V_2}{V_1}} \quad \phi_2(y) = \frac{\phi(y)}{1 - \frac{V_1}{V_2}}$$



# Design Theory

➡ Why two doublets? Simple – I had to split the powers of the first doublet so that surface curvatures are reduced, yielding a ***freeform progressive*** Petzval system, optimized across three stop positions in  $y$



# Simulated Image (assume 100% contrast LCD)

OBJECT

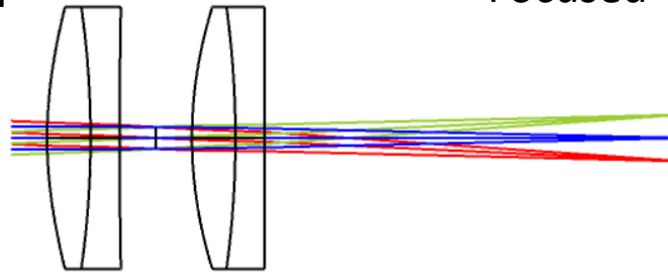
DISTANCE

IMAGE



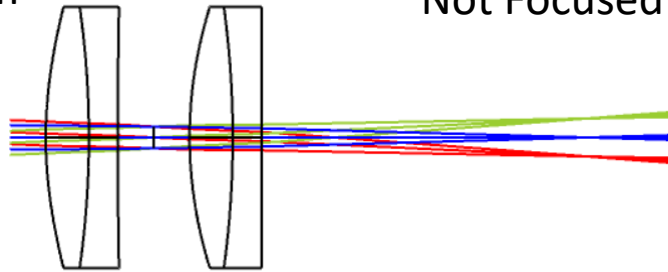
250 mm

Focused



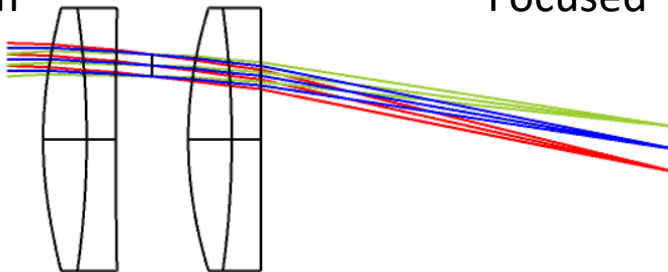
1000 mm

Not Focused



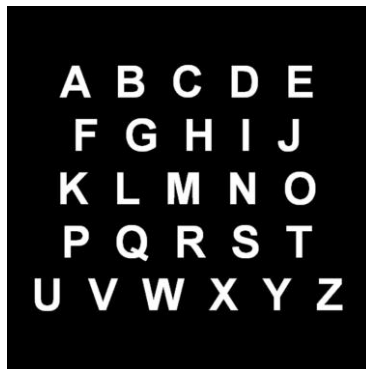
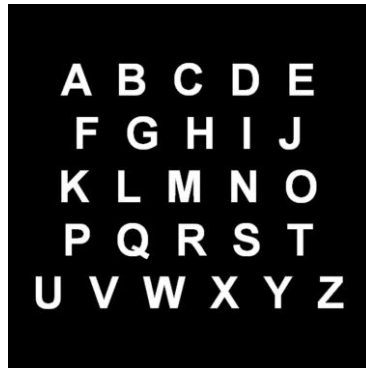
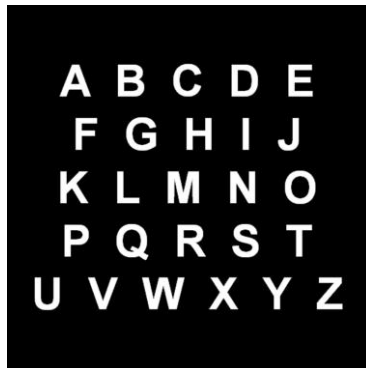
1000 mm

Focused



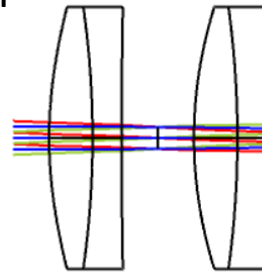
# Simulated Image (assume 100% contrast LCD)

OBJECT



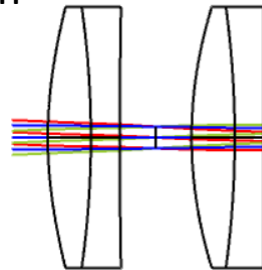
DISTANCE

250 mm



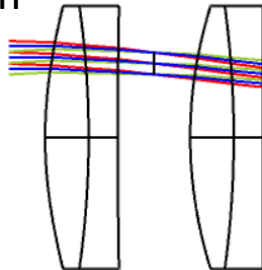
Focused

1000 mm



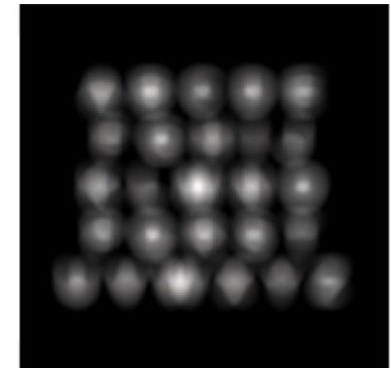
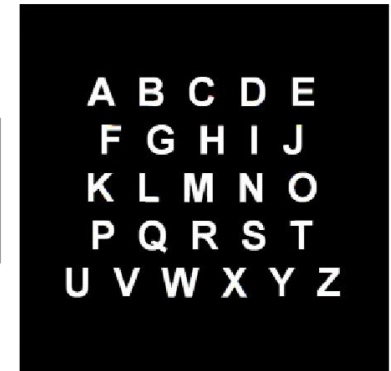
Not Focused

1000 mm

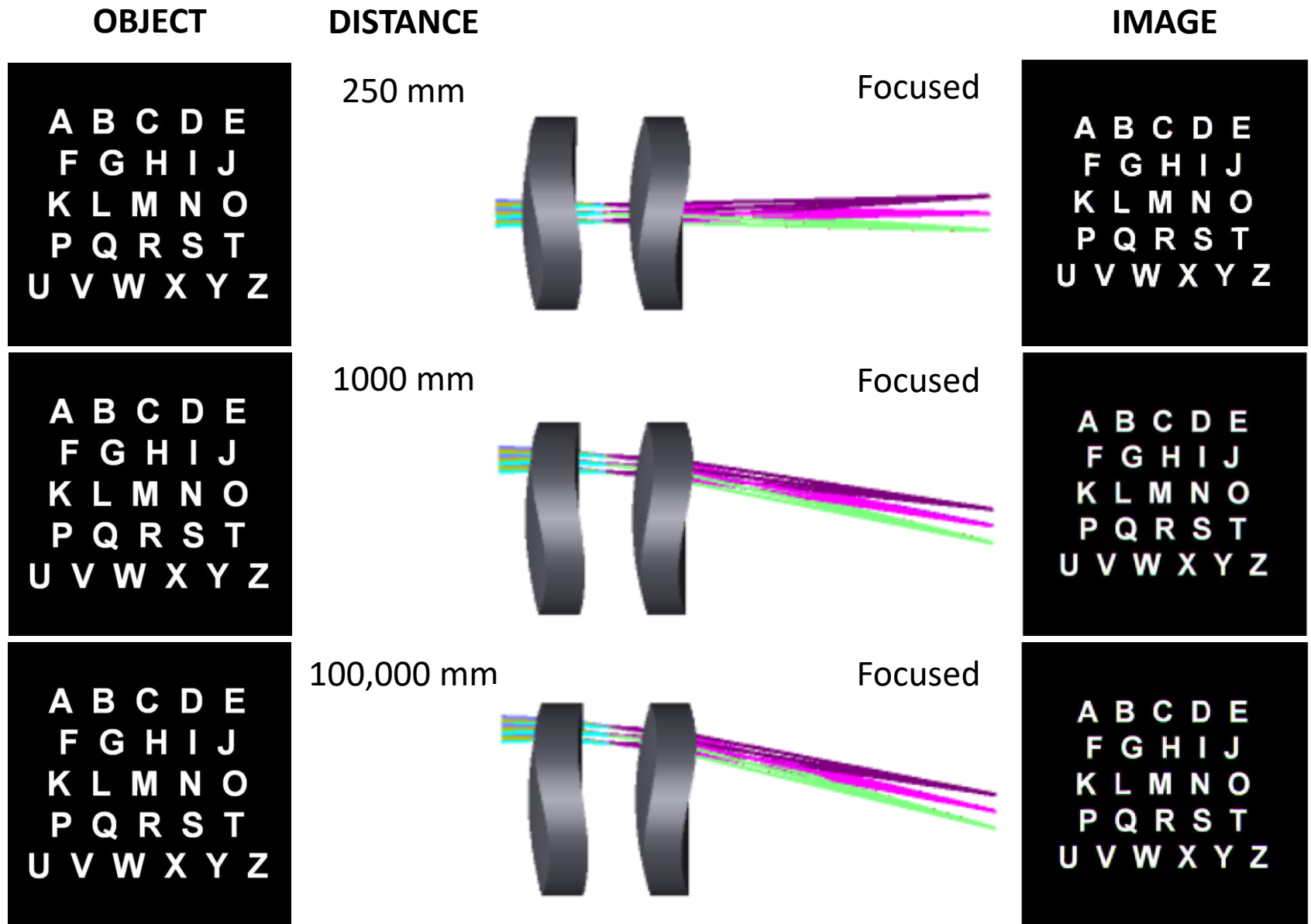


Focused

IMAGE



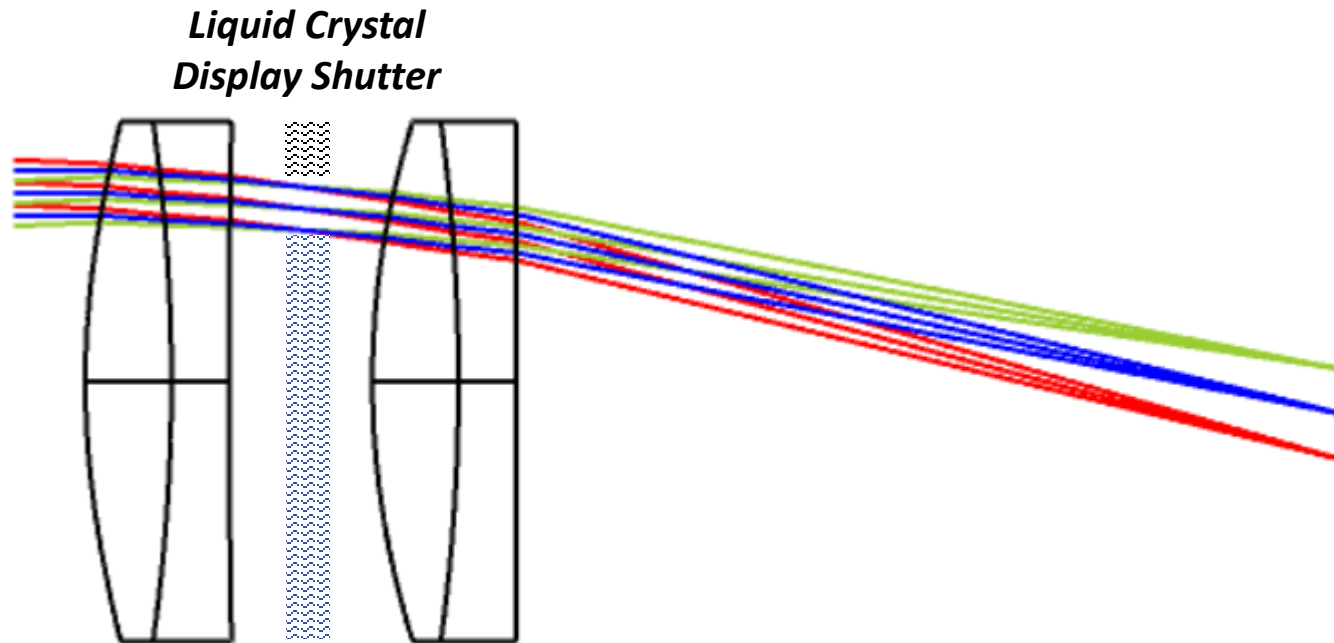
# Simulated Image (assume 100% contrast LCD)





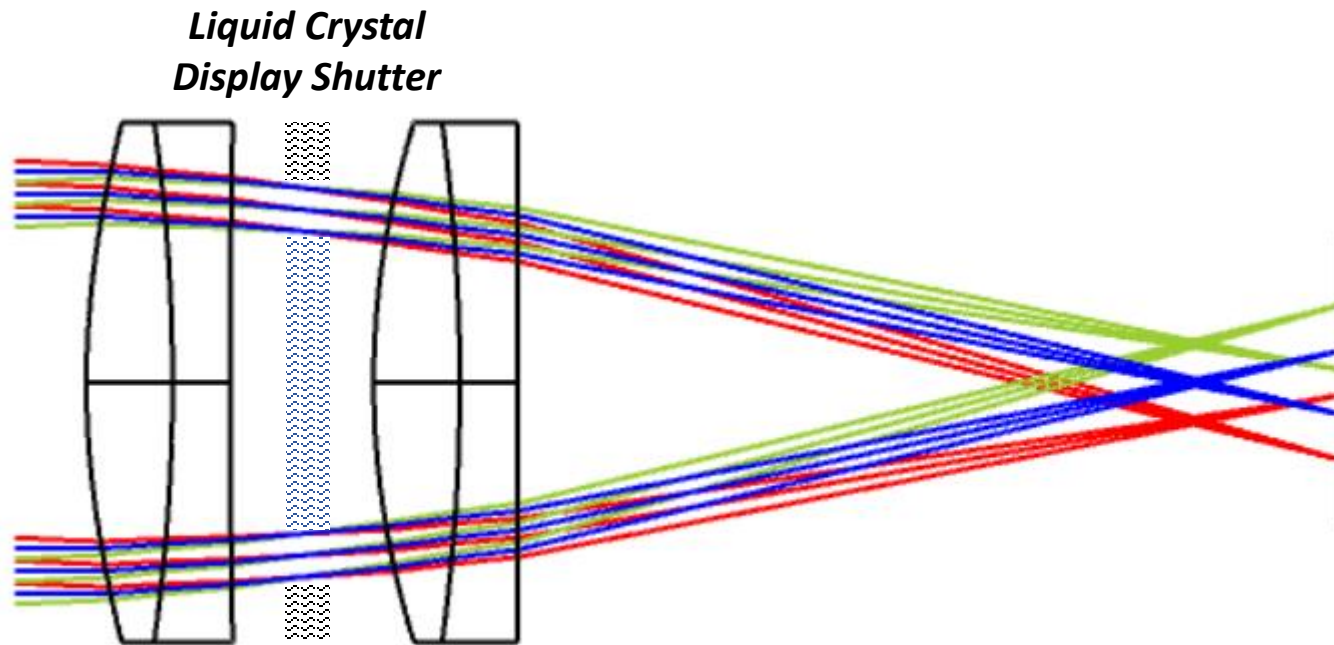
# Potential Applications 1

- ➡ Variable focus without moving parts can be made possible if the stop is generated by a liquid crystal display (LCD) shutter (of course, provided that there is sufficient contrast ratio)



# Potential Applications 2

- ➔ By programming the LCD shutter to alternate between left and right shutters, and synchronizing this with a display of the left and right views, a 3D stereo image may be produced in *almost* real-time (and information may be extracted for range determination\*)



\* The sag profile MUST be modified such that the term  $Ayx^2$  is made symmetric about the optic axis

# Problems I have not solved

- ☐ Can you combine freeform surface modelling and ray tracing code with 3D rendering software (say, from Pixar or DreamWorks) and simulate left-right shutter image displays of a 3D object on a computer monitor (or project them onto a non-depolarizing screen)?
- ☐ How do you align such a lens? Apply nodal aberration theory and inspect the aberration field?
- ☐ How large can the NA and field of view get before running into trouble?
- ☐ Can you zoom with such a lens system? If so, how many freeform surfaces would be needed?
- ☐ I ended up with a simple “Petzval-like” design form, but what happens if you applied a double-Gauss or any other forms? Can we extend the performance (and application space)?

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- [1] K. E. Kuijk, "Optical Imaging System Having an Electronically Variable Focal Length and Optical Image Sensor Provided with such a System," U.S. Patent No. 4,927,241, (May 22, 1990).
- [2] T. Gustafsson and S. Zyra, "Lens with Variable Focal Length," WIPO Patent Application No. WO/1998/027448, (Dec. 17, 1997).
- [3] R. Siew, "Progressive lens approach to variable focus without moving parts in electronic imaging systems," Inopticalsolutions Open Access Technical Note (Jan. 14, 2018), doi: <https://dx.doi.org/10.6084/m9.figshare.5786733>.
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- [6] K. Fuerschbach, J. P. Rolland, and K. P. Thompson, "Theory of aberration fields for general optical systems with freeform surfaces," *Opt. Express* **22**(22), 26585 – 26606 (2014).
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- [14] S. Lukes, *Dynamic Agile Focusing in Microscopy: A Review*, (SPIE Press, 2016), pp. 12 – 13.
- [15] W. Chi and N. George, "Electronic imaging using a logarithmic asphere," *Opt. Letters* **26**(12), 875 – 877 (2001).
- [16] K. Khare, *Fourier Optics and Computational Imaging*, (Wiley, 2016), pp. 271 – 273.

**Prior Art**

**Original Work**

**Misc. info on  
freeform lens  
design, nodal  
aberration  
theory...**

**Single lens  
stereo  
imaging**

**More variable  
focus lenses**

# THANK YOU!

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